

Structure of multidimensional constant-shape substitutions

Christopher Cabezas

Université Picardie Jules Verne (LAMFA)

Journées SDA2 2020 : Systèmes Dynamiques, Automates & Algorithmes

04 Decembre 2020

- 1 Definitions and basic properties
- 2 Homomorphisms between multidimensional constant-shape substitutions
 - Consequences of Main Theorem and Examples

Let $L : \mathbb{R}^d \rightarrow \mathbb{R}^d$ be an expansion linear map, i.e., $\|L\| > 1$ and $\|L^{-1}\| < 1$ such that $L(\mathbb{Z}^d) \subseteq \mathbb{Z}^d$. Let $F = L([0, 1)^d) \cap \mathbb{Z}^d$, and \mathcal{A} be a finite alphabet.

Let $L : \mathbb{R}^d \rightarrow \mathbb{R}^d$ be an expansion linear map, i.e., $\|L\| > 1$ and $\|L^{-1}\| < 1$ such that $L(\mathbb{Z}^d) \subseteq \mathbb{Z}^d$. Let $F = L([0, 1)^d) \cap \mathbb{Z}^d$, and \mathcal{A} be a finite alphabet.

A **multidimensional constant-shape substitution** ζ is a map $\mathcal{A} \rightarrow \mathcal{A}^F$. F is the **support** of the substitution.

Let $L : \mathbb{R}^d \rightarrow \mathbb{R}^d$ be an expansion linear map, i.e., $\|L\| > 1$ and $\|L^{-1}\| < 1$ such that $L(\mathbb{Z}^d) \subseteq \mathbb{Z}^d$. Let $F = L([0, 1)^d) \cap \mathbb{Z}^d$, and \mathcal{A} be a finite alphabet.

A **multidimensional constant-shape substitution** ζ is a map $\mathcal{A} \rightarrow \mathcal{A}^F$. F is the **support** of the substitution.

Every $\mathbf{p} \in \mathbb{Z}^d$ can be written in a unique way as $\mathbf{p} = L(\mathbf{j}) + \mathbf{k}$, with $\mathbf{j} \in \mathbb{Z}^d$ and $\mathbf{k} \in F$. We consider the substitution ζ as a map from $\mathcal{A}^{\mathbb{Z}^d}$ to itself given by

$$\zeta(x)_{L(\mathbf{j})+\mathbf{k}} = \zeta(x(\mathbf{j}))_{\mathbf{k}}.$$

Example of a multidimensional constant-shape substitution:

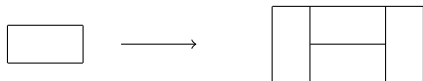
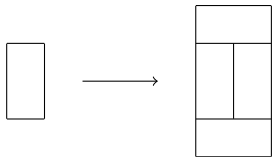
$$L = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}, F = \llbracket 0, 1 \rrbracket \times \llbracket 0, 2 \rrbracket \text{ and}$$

$$a \mapsto \begin{array}{cc} b & c \\ c & b \\ a & b \end{array}$$

$$b \mapsto \begin{array}{cc} a & c \\ c & b \\ b & c \end{array}$$

$$c \mapsto \begin{array}{cc} c & b \\ a & c \\ c & b \end{array}.$$

The table tiling:



For any $n > 0$ the n -th iteration is defined as $\zeta^n : \mathcal{A} \rightarrow \mathcal{A}^{F_n^\zeta}$, with $F_{n+1}^\zeta = L_\zeta(F_n^\zeta) + F_1^\zeta$.

For any $n > 0$ the n -th iteration is defined as $\zeta^n : \mathcal{A} \rightarrow \mathcal{A}^{F_n^\zeta}$, with $F_{n+1}^\zeta = L_\zeta(F_n^\zeta) + F_1^\zeta$.

A substitution is **primitive** if there exists a positive integer $n > 0$, such that for every $a, b \in \mathcal{A}$, b occurs in $\zeta^n(a)$.

For any $n > 0$ the n -th iteration is defined as $\zeta^n : \mathcal{A} \rightarrow \mathcal{A}^{F_n^\zeta}$, with $F_{n+1}^\zeta = L_\zeta(F_n^\zeta) + F_1^\zeta$.

A substitution is **primitive** if there exists a positive integer $n > 0$, such that for every $a, b \in \mathcal{A}$, b occurs in $\zeta^n(a)$.

The **language** of a substitution is the set

$$\mathcal{L}_\zeta = \{p \sqsubseteq \zeta^n(a), \text{ for some } n > 0, a \in \mathcal{A}\}.$$

For any $n > 0$ the n -th iteration is defined as $\zeta^n : \mathcal{A} \rightarrow \mathcal{A}^{F_n^\zeta}$, with $F_{n+1}^\zeta = L_\zeta(F_n^\zeta) + F_1^\zeta$.

A substitution is **primitive** if there exists a positive integer $n > 0$, such that for every $a, b \in \mathcal{A}$, b occurs in $\zeta^n(a)$.

The **language** of a substitution is the set

$$\mathcal{L}_\zeta = \{p \sqsubseteq \zeta^n(a), \text{ for some } n > 0, a \in \mathcal{A}\}.$$

With the language we define the subshift $(X_\zeta, S, \mathbb{Z}^d)$ as the set of all sequences $x \in \mathcal{A}^{\mathbb{Z}^d}$ such that every pattern of x is in \mathcal{L}_ζ .

The system $(X_\zeta, T, \mathbb{Z}^d)$ is uniquely ergodic, i.e., there exists an unique T -invariant measure μ_ζ (which is also ergodic).

The system $(X_\zeta, T, \mathbb{Z}^d)$ is uniquely ergodic, i.e., there exists a unique T -invariant measure μ_ζ (which is also ergodic).

P. Michel (1974) proved the one-dimensional case.

B. Solomyak (1997) proved it for self-affine tilings with the \mathbb{R}^d -action

J.-Y. Lee, R. Moody, B. Solomyak (2003) proved it for Substitution Delone sets with \mathbb{R}^d -actions.

A **homomorphism** is a continuous surjective map $\phi : X \rightarrow Y$ that commutes with the action, i.e., $T^n \circ \phi(x) = \phi \circ T^n(x)$ for all $x \in X$ and $n \in \mathbb{Z}^d$. We denote the set of all homomorphisms as $\text{Hom}(X, Y, T, \mathbb{Z}^d)$.

If $X = Y$, ϕ is called an **endomorphism** and if ϕ is invertible, ϕ is called an **automorphism**. We denote the set of all automorphisms as $\text{Aut}(X, T, \mathbb{Z}^d)$.

We use $m\text{Hom}$ or $m\text{Aut}$ for measurable maps.

It is well known that homomorphisms between symbolic systems are characterized:

Theorem (Curtis-Hedlund-Lyndon)

Let (X, S, \mathbb{Z}^d) and (Y, S, \mathbb{Z}^d) be two subshifts. A map $\phi : (X, S, \mathbb{Z}^d) \rightarrow (Y, S, \mathbb{Z}^d)$ is a factor map if and only if there exists a $B(0, r)$ -block map $\Phi : \mathcal{L}_{B(0, r)}(X) \rightarrow \mathcal{L}_1(Y)$, such that $\phi(x)_{\mathbf{n}} = \Phi(x|_{\mathbf{n}+B(0, r)})$, for all $\mathbf{n} \in \mathbb{Z}^d$ and $x \in X$ (i.e., ϕ is a sliding block code).

Theorem (Main Theorem)

Let $(X_{\zeta_1}, S, \mathbb{Z}^d)$, $(X_{\zeta_2}, S, \mathbb{Z}^d)$ be two substitution dynamical system with ζ_1, ζ_2 having the same expansion map L . If $(X_{\zeta_2}, S, \mathbb{Z}^d)$ does not have purely discrete spectrum, then for every $\phi \in m\text{Hom}(X_{\zeta_1}, X_{\zeta_2}, S, \mathbb{Z}^d)$ there exists $\mathbf{j} \in \mathbb{Z}^d$ with $S^{\mathbf{j}}\phi$ equals to $\psi \in \text{Hom}(X_{\zeta_1}, X_{\zeta_2}, S, \mathbb{Z}^d)$ μ_{ζ_1} -a.e., satisfying the following two properties:

- 1 ψ is a sliding block code of radius \sqrt{d} .
- 2 There exist an integer $n > 0$ and $\mathbf{p} \in \mathbb{Z}^d$ such that $S^{\mathbf{p}}\psi\zeta_1^n = \zeta_2^n\psi$.

Theorem (Main Theorem)

Let $(X_{\zeta_1}, S, \mathbb{Z}^d)$, $(X_{\zeta_2}, S, \mathbb{Z}^d)$ be two substitution dynamical system with ζ_1, ζ_2 having the same expansion map L . If $(X_{\zeta_2}, S, \mathbb{Z}^d)$ does not have purely discrete spectrum, then for every $\phi \in m\text{Hom}(X_{\zeta_1}, X_{\zeta_2}, S, \mathbb{Z}^d)$ there exists $\mathbf{j} \in \mathbb{Z}^d$ with $S^{\mathbf{j}}\phi$ equals to $\psi \in \text{Hom}(X_{\zeta_1}, X_{\zeta_2}, S, \mathbb{Z}^d)$ μ_{ζ_1} -a.e., satisfying the following two properties:

- 1 ψ is a sliding block code of radius \sqrt{d} .
- 2 There exist an integer $n > 0$ and $\mathbf{p} \in \mathbb{Z}^d$ such that $S^{\mathbf{p}}\psi\zeta_1^n = \zeta_2^n\psi$.

This was first proved by **B. Host and F. Parreau** (1989) for constant-length in the one-dimensional case.

Corollary

Let ζ be an aperiodic multidimensional constant-shape substitution with spectrum not purely discrete. Then $(X_\zeta, S, \mathbb{Z}^d)$ is coalescent.

Corollary

Let ζ be an aperiodic multidimensional constant-shape substitution with spectrum not purely discrete. Then $(X_\zeta, S, \mathbb{Z}^d)$ is coalescent.

Corollary

Let $(X_\zeta, S, \mathbb{Z}^d)$ be a subshift from aperiodic substitution ζ with not purely discrete spectrum. Then $\text{Aut}(X_\zeta, S, \mathbb{Z}^d)$ is virtually \mathbb{Z}^d , i.e., $|\text{Aut}(X_\zeta, \mathbb{Z}^d) / \langle S \rangle| < \infty$.

Both results are also consequences of the following result

Proposition

Let ζ be a substitution. Then, there exist finitely many ζ -invariant orbits. The bound is an explicit formula which only depends on $|\mathcal{A}|$, $\|L_\zeta^{-1}\|$ and $\det(L_\zeta - \text{id})$.

Both results are also consequences of the following result

Proposition

Let ζ be a substitution. Then, there exist finitely many ζ -invariant orbits. The bound is an explicit formula which only depends on $|\mathcal{A}|$, $\|L_\zeta^{-1}\|$ and $\det(L_\zeta - \text{id})$.

An orbit $\mathcal{O}(x, \mathbb{Z}^d)$ is called **ζ -invariant** if there exists $\mathbf{j} \in \mathbb{Z}^d$ such that $\zeta(x) = S^{\mathbf{j}}x$ (The definition is independent of the choice of the point in the orbit of x).

Both results are also consequences of the following result

Proposition

Let ζ be a substitution. Then, there exist finitely many ζ -invariant orbits. The bound is an explicit formula which only depends on $|\mathcal{A}|$, $\|L_\zeta^{-1}\|$ and $\det(L_\zeta - \text{id})$.

An orbit $\mathcal{O}(x, \mathbb{Z}^d)$ is called **ζ -invariant** if there exists $\mathbf{j} \in \mathbb{Z}^d$ such that $\zeta(x) = S^{\mathbf{j}}x$ (The definition is independent of the choice of the point in the orbit of x).

Remark

If $L_\zeta = 2 \text{id}_{\mathbb{R}^d}$ the only ζ -invariant orbits are the ones given by the fixed points of the substitution.

Proposition

If ζ is an aperiodic primitive substitution, there exists a finite number of aperiodic symbolic factors with spectrum not purely discrete

Proposition

If ζ is an aperiodic primitive substitution, there exists a finite number of aperiodic symbolic factors with spectrum not purely discrete (which in fact are conjugate to primitive multidimensional constant-shape substitutions).

Proposition

If ζ is an aperiodic primitive substitution, there exists a finite number of aperiodic symbolic factors with spectrum not purely discrete (which in fact are conjugate to primitive multidimensional constant-shape substitutions).

This was first proved by **F. Durand** (2000) for the one-dimensional case.

In the one-dimensional case, this results are consequences of substitutions being **linearly recurrent**.

In the one-dimensional case, these results are consequences of substitutions being **linearly recurrent**.

The **repetitivity function** of a substitution is the map $M_{X_\zeta} : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ defined for $R > 0$ as the smallest radius such that every ball $B(\mathbf{n}, M_{X_\zeta}(R))$ contains an occurrence of every pattern with $\text{diam}(\text{supp}(p)) \leq 2R$.

In the one-dimensional case, these results are consequences of substitutions being **linearly recurrent**.

The **repetitivity function** of a substitution is the map $M_{X_\zeta} : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ defined for $R > 0$ as the smallest radius such that every ball $B(\mathbf{n}, M_{X_\zeta}(R))$ contains an occurrence of every pattern with $\text{diam}(\text{supp}(p)) \leq 2R$.

We say that the substitution is **linearly recurrent** or **linearly repetitive** if the repetitivity function has a linear growth, i.e., there exists $C > 0$ such that $M_{X_\zeta}(R) \leq C \cdot R$.

Example of a non linearly recurrent substitution: $L = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$,

$F = \llbracket 0, 1 \rrbracket \times \llbracket 0, 2 \rrbracket$ and

$$a \mapsto \begin{array}{cc} b & c \\ c & b \\ a & b \end{array}$$

$$b \mapsto \begin{array}{cc} a & c \\ c & b \\ b & c \end{array}$$

$$c \mapsto \begin{array}{cc} c & b \\ a & c \\ c & b \end{array} .$$

Example of a non linearly recurrent substitution: $L = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$,
 $F = \llbracket 0, 1 \rrbracket \times \llbracket 0, 2 \rrbracket$ and

$$a \mapsto \begin{matrix} b & c \\ c & b \\ a & b \end{matrix}$$

$$b \mapsto \begin{matrix} a & c \\ c & b \\ b & c \end{matrix}$$

$$c \mapsto \begin{matrix} c & b \\ a & c \\ c & b \end{matrix}.$$

Lemma

Let ζ be an aperiodic primitive substitution, then $M_{X_\zeta}(R)$ is

$$\mathcal{O} \left(R^{-\frac{\log(\|L_\zeta\|)}{\log(\|L_\zeta^{-1}\|)}} \right).$$

Remark

- ① *If the expansion map is symmetric, then*

$M_{X_\zeta}(R) = \mathcal{O} \left(R^{\frac{\log(|\lambda_1|)}{\log(|\lambda_d|)}} \right)$, where $|\lambda_1|$, $|\lambda_d|$ are the maximum and minimum of the absolute values of the eigenvalues of L_ζ , respectively.

Remark

- ① *If the expansion map is symmetric, then*

$M_{X_\zeta}(R) = \mathcal{O} \left(R^{\frac{\log(|\lambda_1|)}{\log(|\lambda_d|)}} \right)$, where $|\lambda_1|$, $|\lambda_d|$ are the maximum and minimum of the absolute values of the eigenvalues of L_ζ , respectively.

- ② *In the case of a self-similar tiling, i.e. $\|L_\zeta\| = \|L_\zeta^{-1}\|^{-1} = \lambda$, substitutions are linearly recurrent.*

THE END